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CUET · MATHEMATICS · CLASS XII · CODE 319

Vector Algebra

CUET unit: Vector Algebra

By UniDrill · NCERT-grounded study material

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The logo for UniDrill, featuring the word "UniDrill" in a sans-serif font. "Uni" is in blue and "Drill" is in orange. The logo is centered on a white background with a faint, light blue shield-like shape behind it.

Snapshot

- Distinguishes scalar quantities (magnitude only — length, mass, time, speed) from vector quantities (magnitude + direction — displacement, velocity, force) and develops the directed-line-segment model.
- Builds the algebra of vectors in three-dimensional space using the standard basis $\hat{i}, \hat{j}, \hat{k}$, with position vectors of points and the formula $|r| = \sqrt{(x^2 + y^2 + z^2)}$.
- Establishes operations — addition (triangle, parallelogram, polygon laws), scalar multiplication, section formula, scalar (dot) product, and vector (cross) product — with their properties.
- Connects the dot product to angle/projection/perpendicularity, and the cross product to area of triangles/parallelograms, parallelism, and right-handed orientation.
- CUET frequently tests numerical computation of dot/cross products, angles, projections, unit vectors, direction cosines, section-formula points, and areas — the work is computation-heavy and formula-driven.

Detailed Notes

2.1 Core concepts

- A scalar has only magnitude (e.g. length, mass, time, speed, volume), while a vector has both magnitude and direction (e.g. displacement, velocity, force, momentum) (NCERT §10.1, p. 338).
- A directed line segment from initial point A to terminal point B is a vector denoted \vec{AB} ; its magnitude $|\vec{AB}|$ is the distance between A and B, and is never negative (NCERT §10.2, p. 339).
- For a point $P(x, y, z)$, the position vector \vec{OP} has magnitude $|\vec{OP}| = \sqrt{(x^2 + y^2 + z^2)}$ with respect to origin O (NCERT §10.2 Position Vector, p. 339).
- The direction angles α, β, γ are the angles \vec{OP} makes with the positive x-, y-, z-axes; $l = \cos \alpha, m = \cos \beta, n = \cos \gamma$ are the direction cosines, and lr, mr, nr (proportional to l, m, n) are the direction ratios a, b, c (NCERT §10.2 Direction Cosines, p. 340).
- The identity $l^2 + m^2 + n^2 = 1$ always holds, but in general $a^2 + b^2 + c^2 \neq 1$ (NCERT §10.2 Note, p. 341).

- Types of vectors — Zero vector (coincident initial/terminal points, no definite direction); Unit vector (magnitude 1, denoted \hat{a}); Coinitial vectors (same initial point); Collinear vectors (parallel to the same line); Equal vectors (same magnitude and direction); Negative of a vector (same magnitude, opposite direction) (NCERT §10.3, p. 341).
- Free vectors — any vector may be displaced parallel to itself without changing its magnitude or direction; throughout this topic we deal with free vectors only (NCERT §10.3 Remark, p. 341).
- Triangle law of vector addition — if a girl moves $A \rightarrow B \rightarrow C$, then $AB + BC = AC$ (NCERT §10.4, p. 343).
- Parallelogram law — if two vectors are represented by two adjacent sides of a parallelogram, their sum is the diagonal through their common point; the two laws are equivalent (NCERT §10.4, p. 344).
- Properties of vector addition — commutative ($a + b = b + a$) and associative ($(a + b) + c = a + (b + c)$); zero vector is the additive identity (NCERT §10.4 Properties, pp. 344–346).
- Multiplication by scalar λ — λa is collinear to a , has magnitude $|\lambda||a|$, and the same direction as a if $\lambda > 0$ or opposite direction if $\lambda < 0$; when $\lambda = 1/|a|$, λa gives the unit vector $\hat{a} = a/|a|$ (NCERT §10.5, pp. 346–347).
- Component form — any vector r with terminal point $P(x, y, z)$ is $r = x\hat{i} + y\hat{j} + z\hat{k}$, where x, y, z are scalar components and $|r| = \sqrt{(x^2 + y^2 + z^2)}$ (NCERT §10.5.1, pp. 347–348).
- Two vectors $a = a_1\hat{i} + a_2\hat{j} + a_3\hat{k}$ and $b = b_1\hat{i} + b_2\hat{j} + b_3\hat{k}$ are equal iff $a_1 = b_1, a_2 = b_2, a_3 = b_3$; they are collinear iff $b_1/a_1 = b_2/a_2 = b_3/a_3 = \lambda$ (NCERT §10.5.1, pp. 348–349).
- Vector joining two points — $P_1P_2 = (x_2 - x_1)\hat{i} + (y_2 - y_1)\hat{j} + (z_2 - z_1)\hat{k}$ with magnitude $\sqrt{(x_2 - x_1)^2 + (y_2 - y_1)^2 + (z_2 - z_1)^2}$ (NCERT §10.5.2, p. 351).
- Section formula (internal) — point R dividing PQ internally in ratio $m:n$ has position vector $(mb + na)/(m + n)$; (external) — $(mb - na)/(m - n)$; midpoint = $(a + b)/2$ (NCERT §10.5.3, pp. 352–353).
- Scalar (dot) product — $a \cdot b = |a||b| \cos \theta$, where θ is the angle between a and b ; result is a scalar (NCERT §10.6.1, p. 355).
- Dot-product observations — $a \cdot b = 0$ iff $a \perp b$ (for nonzero vectors); $a \cdot a = |a|^2$; commutative ($a \cdot b = b \cdot a$); distributive over addition; $\hat{i} \cdot \hat{i} = \hat{j} \cdot \hat{j} = \hat{k} \cdot \hat{k} = 1$ and $\hat{i} \cdot \hat{j} = \hat{j} \cdot \hat{k} = \hat{k} \cdot \hat{i} = 0$ (NCERT §10.6.1, pp. 356–357).
- Component form of dot product — $a \cdot b = a_1b_1 + a_2b_2 + a_3b_3$; angle $\cos \theta = (a \cdot b)/(|a||b|)$ (NCERT §10.6.1, p. 357).
- Projection of a vector — projection of a on a directed line with unit vector \hat{p} is $a \cdot \hat{p}$; projection of a on vector b is $(a \cdot b)/|b|$ (NCERT §10.6.2, pp. 357–358).

- Vector (cross) product — $a \times b = |a||b| \sin \theta \hat{n}$, where \hat{n} is a unit vector perpendicular to both a and b such that (a, b, \hat{n}) forms a right-handed system; result is a vector (NCERT §10.6.3, p. 363).
- Cross-product observations — $a \times b = 0$ iff $a \parallel b$ (for nonzero vectors); not commutative — $a \times b = -b \times a$ (anti-commutative); distributive over addition; $\hat{i} \times \hat{i} = \hat{j} \times \hat{j} = \hat{k} \times \hat{k} = 0$; $\hat{i} \times \hat{j} = \hat{k}$, $\hat{j} \times \hat{k} = \hat{i}$, $\hat{k} \times \hat{i} = \hat{j}$ (NCERT §10.6.3, pp. 363–365).
- Area applications — area of triangle with adjacent sides a, b is $\frac{1}{2}|a \times b|$; area of parallelogram with adjacent sides a, b is $|a \times b|$ (NCERT §10.6.3 Observations 8–9, p. 365).
- Determinant form — $a \times b = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ a_1 & a_2 & a_3 \\ b_1 & b_2 & b_3 \end{vmatrix}$; angle via $\sin \theta = |a \times b| / (|a||b|)$ (NCERT §10.6.3, pp. 363, 366).

2.2 Definitions to memorise

Term	Definition	Page
Scalar	Quantity with only magnitude (real number)	338
Vector	Quantity with both magnitude and direction	339
Position vector of $P(x, y, z)$	OP with $ OP = \sqrt{x^2 + y^2 + z^2}$	339
Direction cosines (l, m, n)	$\cos \alpha, \cos \beta, \cos \gamma$ with x -, y -, z -axes; $l^2 + m^2 + n^2 = 1$	340–341
Direction ratios (a, b, c)	Numbers proportional to direction cosines (lr, mr, nr)	340
Zero vector	Initial and terminal points coincide; magnitude 0; no definite direction	341
Unit vector	Vector with magnitude 1; for vector a , $\hat{a} = a/ a $	341, 347
Coinitial vectors	Two or more vectors with the same initial point	341
Collinear vectors	Two or more vectors parallel to the same line	341
Equal vectors	Same magnitude and same direction	341
Negative of a vector	Same magnitude, opposite direction	341
Free vector	Vector subject to parallel displacement without change	341
Triangle law	$AB + BC = AC$	343
Parallelogram law	Sum of two coinital vectors = diagonal of parallelogram on those sides	344
Scalar (dot) product	$a \cdot b = a b \cos \theta$ (scalar)	355
Projection of a on b	$(a \cdot b) / b $	358
Vector (cross) product		363

Term	Definition	Page
	$\mathbf{a} \times \mathbf{b} = \mathbf{a} \mathbf{b} \sin \theta \hat{n}$ (vector); $\hat{n} \perp$ both, right-handed	
Section formula (internal)	$R = \frac{mb + na}{m + n}$	352
Section formula (external)	$R = \frac{mb - na}{m - n}$	353
Area of triangle (vectors \mathbf{a} , \mathbf{b})	$\frac{1}{2} \mathbf{a} \times \mathbf{b} $	365
Area of parallelogram (sides \mathbf{a} , \mathbf{b})	$ \mathbf{a} \times \mathbf{b} $	365

2.3 Diagrams / processes to remember

- **Fig 10.1 (p. 339):** Directed line, directed line segment AB showing magnitude with arrow direction.
- **Fig 10.2 (p. 340):** Three-dimensional right-handed rectangular coordinate system showing position vectors of points A, B, C with respect to origin O.
- **Fig 10.3 (p. 340):** Direction angles α , β , γ of position vector OP with x-, y-, z-axes; right-angled triangles OAP, OBP, OCP used to derive $l = x/r$, $m = y/r$, $n = z/r$.
- **Fig 10.7–10.8 (pp. 343–344):** Triangle law and polygon-extension for vector addition; subtraction as addition of negative.
- **Fig 10.9–10.10 (pp. 344–345):** Parallelogram law of vector addition; proof of commutativity via parallelogram ABCD.
- **Fig 10.13–10.14 (pp. 347–348):** Unit vectors \hat{i} , \hat{j} , \hat{k} along OX, OY, OZ; component-form derivation by dropping perpendicular foot P_1 .
- **Fig 10.16–10.17 (pp. 352–353):** Internal and external section formula construction.
- **Fig 10.19 (p. 356):** Angle θ between two vectors for scalar product.
- **Fig 10.20 (p. 357):** Projection vector AC for the four cases $0 < \theta < 90^\circ$, $90^\circ < \theta < 180^\circ$, $180^\circ < \theta < 270^\circ$, $270^\circ < \theta < 360^\circ$.
- **Fig 10.22–10.24 (pp. 363–364):** Right-hand rule for cross product; orientation of \hat{i} , \hat{j} , \hat{k} in a right-handed system.
- **Fig 10.26–10.27 (p. 365):** Area of triangle and parallelogram in terms of $|\mathbf{a} \times \mathbf{b}|$.

2.5 Key formulas & theorems

Formula	Statement	NCERT page
Position vector	$OP = x\hat{i} + y\hat{j} + z\hat{k}$	339
Magnitude		r
DCs	$l = \cos \alpha$, $m = \cos \beta$, $n = \cos \gamma$	340

Formula	Statement	NCERT page
DC identity	$l^2 + m^2 + n^2 = 1$	341
Unit vector	$\hat{a} = a/ a $	a
Equal vectors	All components equal	348
Collinear	$b_1/a_1 = b_2/a_2 = b_3/a_3 = \lambda$	349
Vector between two points	$(x_2 - x_1)\hat{i} + (y_2 - y_1)\hat{j} + (z_2 - z_1)\hat{k}$	351
Section formula (internal)	$R = (mb + na)/(m + n)$	352
Section formula (external)	$R = (mb - na)/(m - n)$	353
Midpoint	$(a + b)/2$	353
Dot product	$a \cdot b =$	a
Component dot	$a \cdot b = a_1b_1 + a_2b_2 + a_3b_3$	357
Perpendicularity	$a \cdot b = 0$	356
$a \cdot a$		a
Projection a on b	$(a \cdot b)/ b $	b
Cross product	$a \times b =$	a
Component cross	Determinant with $\hat{i}, \hat{j}, \hat{k}$	363
Anti-commutative	$a \times b = -b \times a$	364
Parallel test	$a \times b = 0$	363
Basis dot products	$\hat{i} \cdot \hat{i} = 1, \hat{i} \cdot \hat{j} = 0$ etc.	357
Basis cross products	$\hat{i} \times \hat{j} = \hat{k}$ etc.	364
Area of parallelogram		$ a \times b $
Area of triangle	$\frac{1}{2}$	$ a \times b $
Triangle law	$\vec{AB} + \vec{BC} = \vec{AC}$	343
Parallelogram law	Sum = diagonal	344

2.6 Solved examples (NCERT-grounded)

Example A (NCERT Example 14, p. 359). Angle between $a = \hat{i} + \hat{j} - \hat{k}$ and $b = \hat{i} - \hat{j} + \hat{k}$.

Step 1 — dot product: $1 \cdot 1 + 1 \cdot (-1) + (-1) \cdot 1 = -1$. **Step 2 — magnitudes:** $|a| = |b| = \sqrt{3}$.

Step 3 — cosine: $\cos \theta = -1/3 \Rightarrow \theta = \cos^{-1}(-1/3)$.

Example B (NCERT Example 24, p. 367). Area of triangle with vertices $A(1,1,1)$, $B(1,2,3)$, $C(2,3,1)$.

Step 1 — vectors: $AB = (0,1,2)$; $AC = (1,2,0)$. **Step 2 — cross product:** $AB \times AC = (1 \cdot 0 - 2 \cdot 2, 2 \cdot 1 - 0 \cdot 0, 0 \cdot 2 - 1 \cdot 1) = (-4, 2, -1)$; magnitude = $\sqrt{21}$. **Step 3 — area:** $\frac{1}{2} \cdot \sqrt{21} = (1/2)\sqrt{21}$ sq units.

Example C (NCERT Exercise 10.3 Q4, p. 361). Projection of $a = \hat{i} + 3\hat{j} + 7\hat{k}$ on $b = 7\hat{i} - \hat{j} + 8\hat{k}$.

Step 1 — dot product: $7 - 3 + 56 = 60$. **Step 2 — $|b|$:** $\sqrt{(49 + 1 + 64)} = \sqrt{114}$. **Step 3 — projection:** $60/\sqrt{114}$.

Example D (NCERT Exercise 10.2 Q14, p. 354). Show $\hat{i} + \hat{j} + \hat{k}$ is equally inclined to axes.

Step 1 — magnitude: $\sqrt{3}$. **Step 2 — DCs:** $(1/\sqrt{3}, 1/\sqrt{3}, 1/\sqrt{3})$. **Step 3 — conclude:** DCs equal \Rightarrow direction angles equal \Rightarrow **equally inclined**.

Example E (Internal section formula). Find R dividing P ($a = \hat{i} + 2\hat{j} + 3\hat{k}$) and Q ($b = 4\hat{i} + 5\hat{j} + 6\hat{k}$) in ratio 2:1.

Step 1 — apply formula: $R = (2 \cdot b + 1 \cdot a)/(2 + 1)$. **Step 2 — numerator:** $2(4\hat{i} + 5\hat{j} + 6\hat{k}) + (\hat{i} + 2\hat{j} + 3\hat{k}) = 9\hat{i} + 12\hat{j} + 15\hat{k}$. **Step 3 — divide by 3:** $R = 3\hat{i} + 4\hat{j} + 5\hat{k}$.

2.4 Common confusions / NTA trap points

- Students confuse direction cosines (l, m, n) with direction ratios (a, b, c) ; remember $l^2 + m^2 + n^2 = 1$ always, but $a^2 + b^2 + c^2 \neq 1$ in general (NCERT §10.2 Note, p. 341).
- "Two collinear vectors are always equal in magnitude" — FALSE. Collinearity needs only parallelism, not equal magnitude (NCERT Exercise 10.1 Q5, p. 342).
- Internal vs external section formula sign — internal uses $\frac{mb + na}{m + n}$, while external uses $\frac{mb - na}{m - n}$. NTA likes to swap these (NCERT §10.5.3, pp. 352–353).
- Dot product is commutative ($a \cdot b = b \cdot a$), but cross product is anti-commutative ($a \times b = -b \times a$). A frequent distractor reverses this (NCERT §10.6.1 Observation 7, p. 356; §10.6.3 Observation 6, p. 364).
- The converse of $a \times b = 0 \Rightarrow a$ or b is zero is NOT true — $a \times b$ can vanish when a is parallel to b without either being zero (NCERT Exercise 10.4 Q8, p. 368).
- Projection of a on b is $(a \cdot b)/|b|$, NOT $(a \cdot b)/|a|$. Students often pick the wrong denominator (NCERT §10.6.2, p. 358).
- For triangle area, the factor is $\frac{1}{2}|a \times b|$, not $|a \times b|$ (which is for parallelogram) — easy to mix up (NCERT §10.6.3, p. 365).

Practice MCQs

PYQ Alignment

Vector Algebra is among the highest-yielding Class XII Mathematics chapters in CUET — typically 8–10 MCQs per paper. Questions cluster around: computing dot/cross products and the angle between two vectors, projection of one vector on another, finding unit vectors and direction cosines, internal/external section formula problems, area of triangles/parallelograms using $|a \times b|$, perpendicularity/parallelism conditions, and statement-based identification of types of vectors. Numerical-answer-style and matching questions appear frequently, so memorising the component-form formulas and the right-handed cross-product cycle $\hat{i} \rightarrow \hat{j} \rightarrow \hat{k}$ pays off.

